


# Structured Linear Model

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# Structured Linear Model

## Problem 1: Evaluation

- What does  $F(x,y)$  look like? 

in a specific form

## Problem 2: Inference

- How to solve the “arg max” problem

$$y = \arg \max_{y \in Y} F(x, y)$$

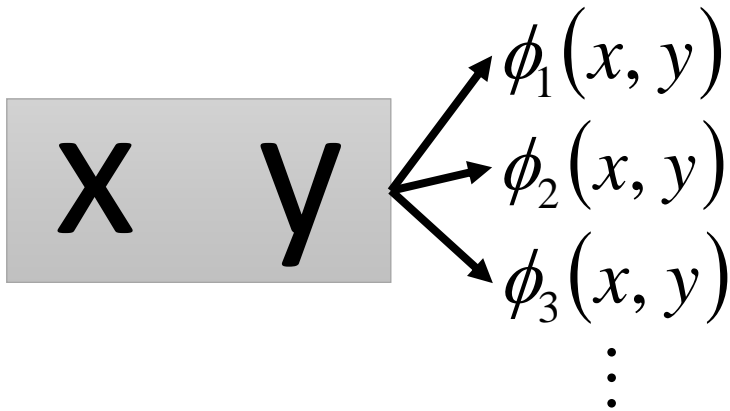
## Problem 3: Training

- Given training data, how to find  $F(x,y)$

# Structured Linear Model: Problem 1

- **Evaluation:** What does  $F(x,y)$  look like?

Characteristics



$$F(x, y) = \begin{bmatrix} w_1 \\ w_2 \\ w_3 \\ \vdots \\ w \end{bmatrix} \cdot \begin{bmatrix} \phi_1(x, y) \\ \phi_2(x, y) \\ \phi_3(x, y) \\ \vdots \\ \phi(x, y) \end{bmatrix}$$

**↓**

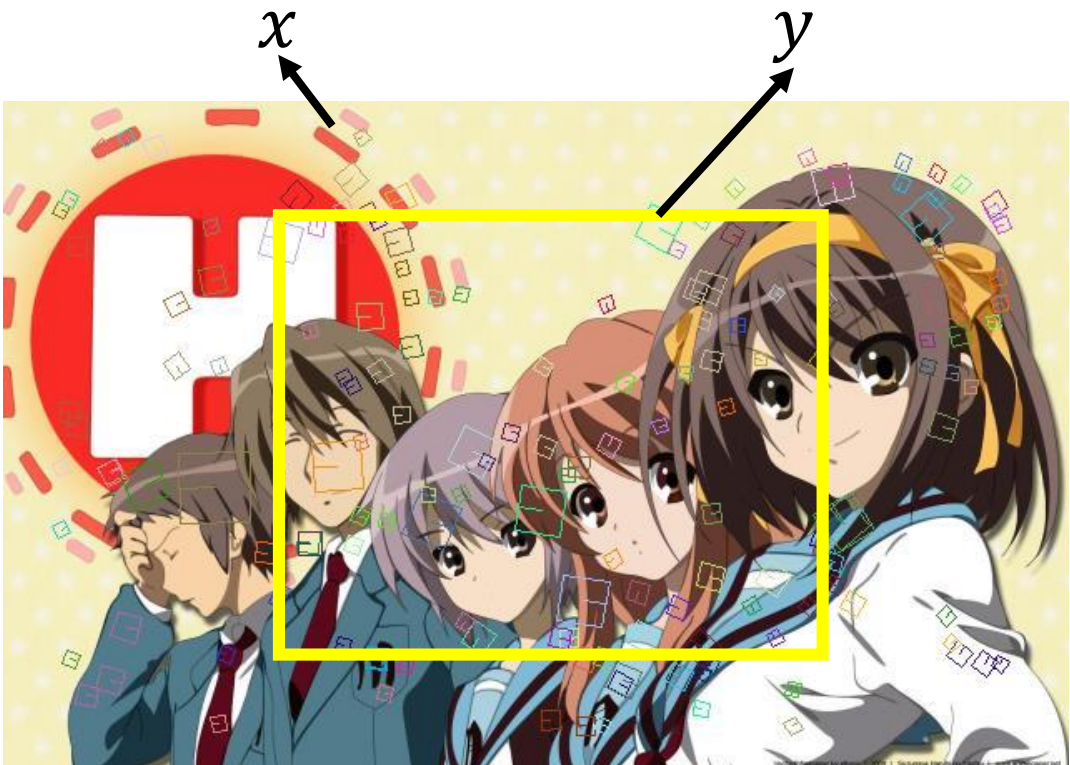
$$F(x, y) = w \cdot \phi(x, y)$$

$$F(x, y) = w_1 \cdot \phi_1(x, y) + w_2 \cdot \phi_2(x, y) + w_3 \cdot \phi_3(x, y) \dots$$

Learning  
from data

# Structured Linear Model: Problem 1

- **Evaluation:** What does  $F(x,y)$  look like?
- Example: **Object Detection**



$\phi($

$) =$

percentage of color red in box  $y$

percentage of color green in box  $y$

percentage of color blue in box  $y$

percentage of color red out of box  $y$

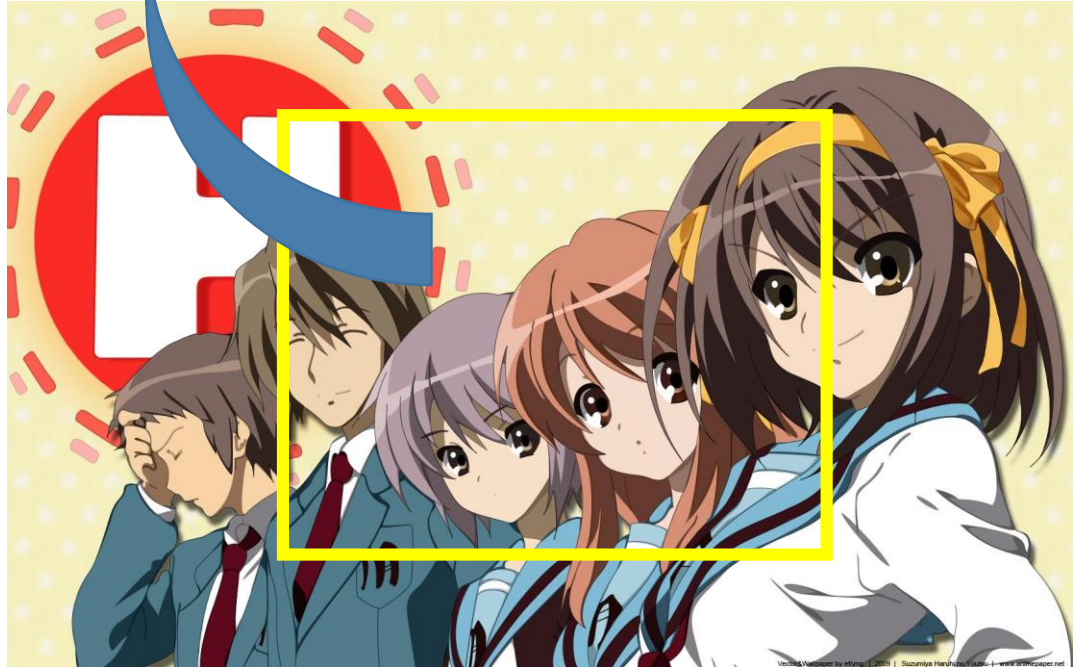
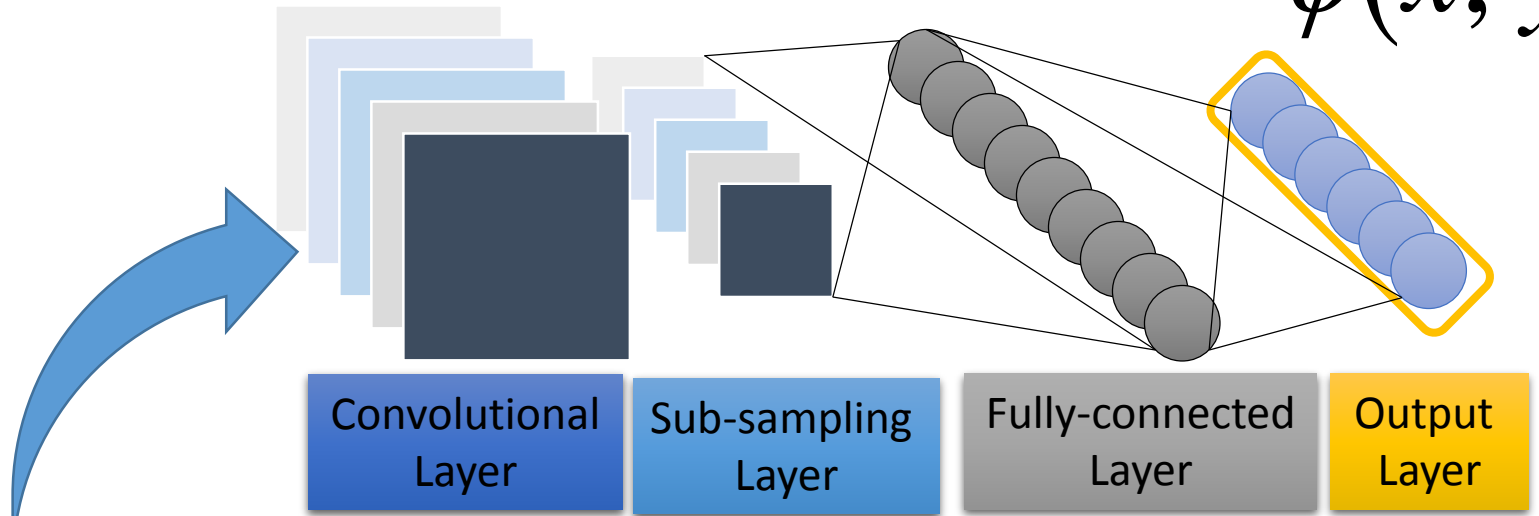
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area of box  $y$

number of specific patterns in box  $y$

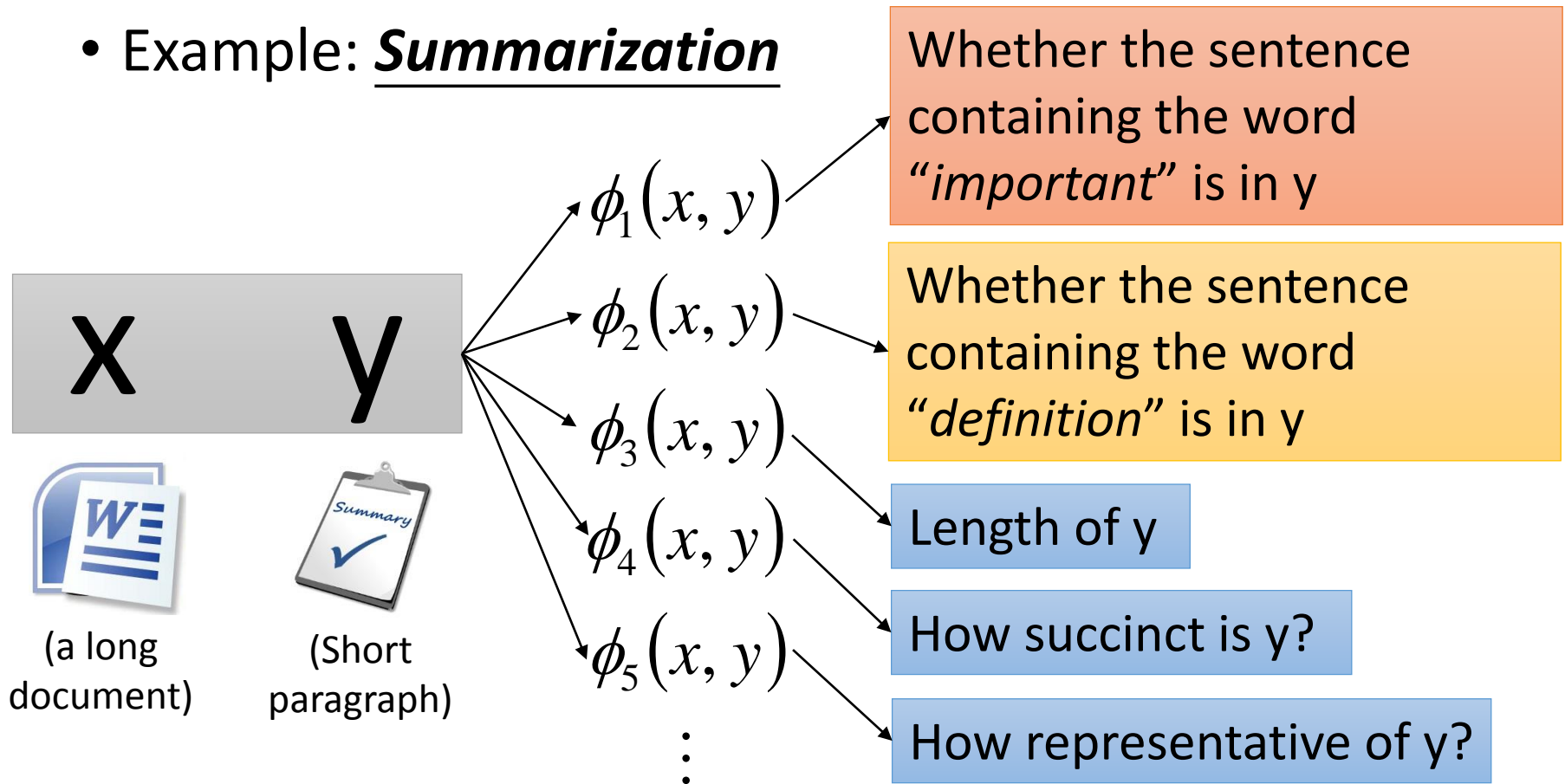
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$$\phi(x, y)$$



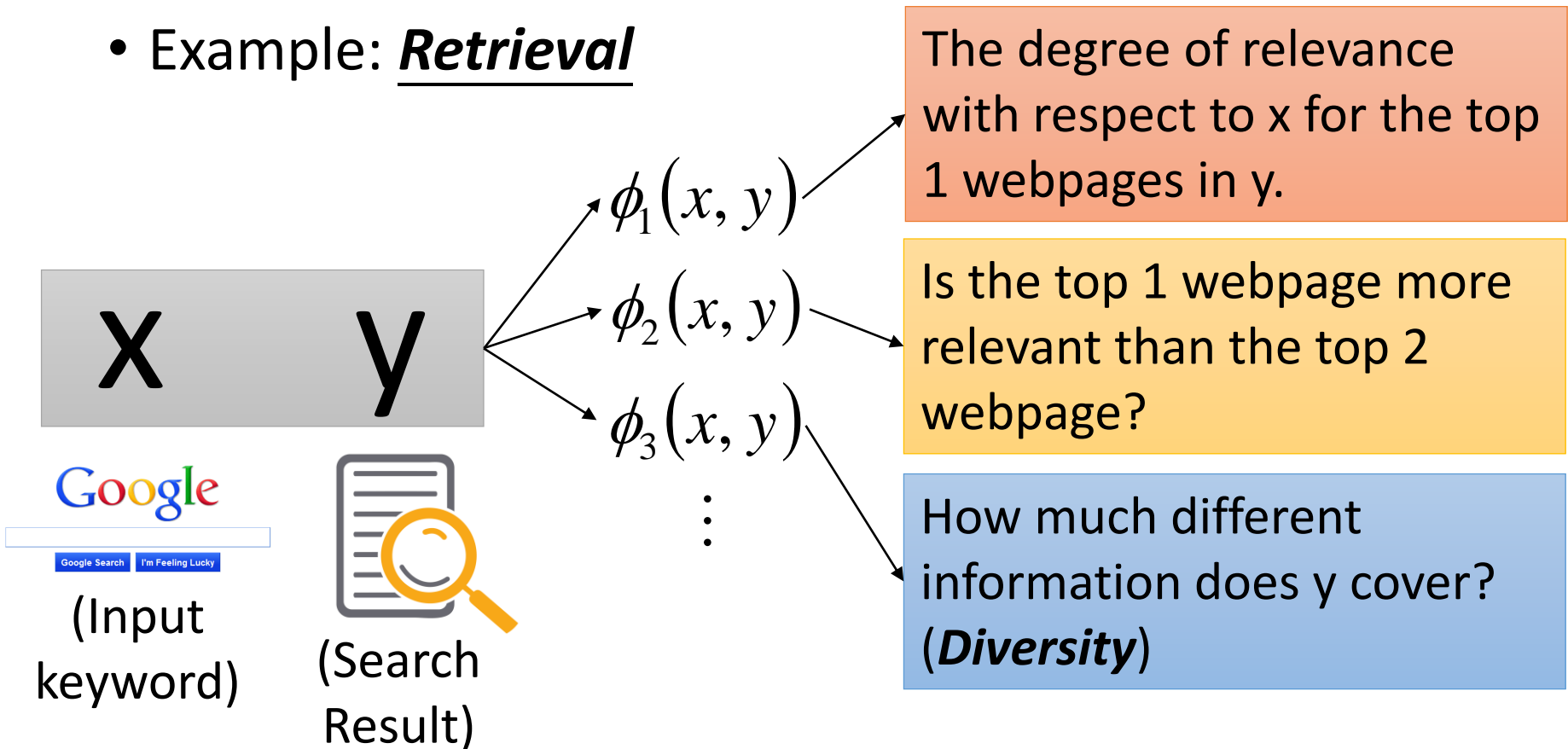
# Structured Linear Model: Problem 1

- **Evaluation:** What does  $F(x,y)$  look like?
- Example: **Summarization**



# Structured Linear Model: Problem 1

- **Evaluation:** What does  $F(x,y)$  look like?
- Example: **Retrieval**



# Structured Linear Model: Problem 2

- **Inference:** How to solve the “arg max” problem

$$y = \arg \max_{y \in Y} F(x, y)$$

$$F(x, y) = w \cdot \phi(x, y) \Rightarrow y = \arg \max_{y \in Y} w \cdot \phi(x, y)$$

- Assume we have solved this question.



# Structured Linear Model:

## Problem 3

- Training: Given training data, how to learn  $F(x,y)$ 
  - $F(x,y) = w \cdot \phi(x,y)$ , so what we have to learn is  $w$

Training data:  $\{(x^1, \hat{y}^1), (x^2, \hat{y}^2), \dots, (x^r, \hat{y}^r), \dots\}$

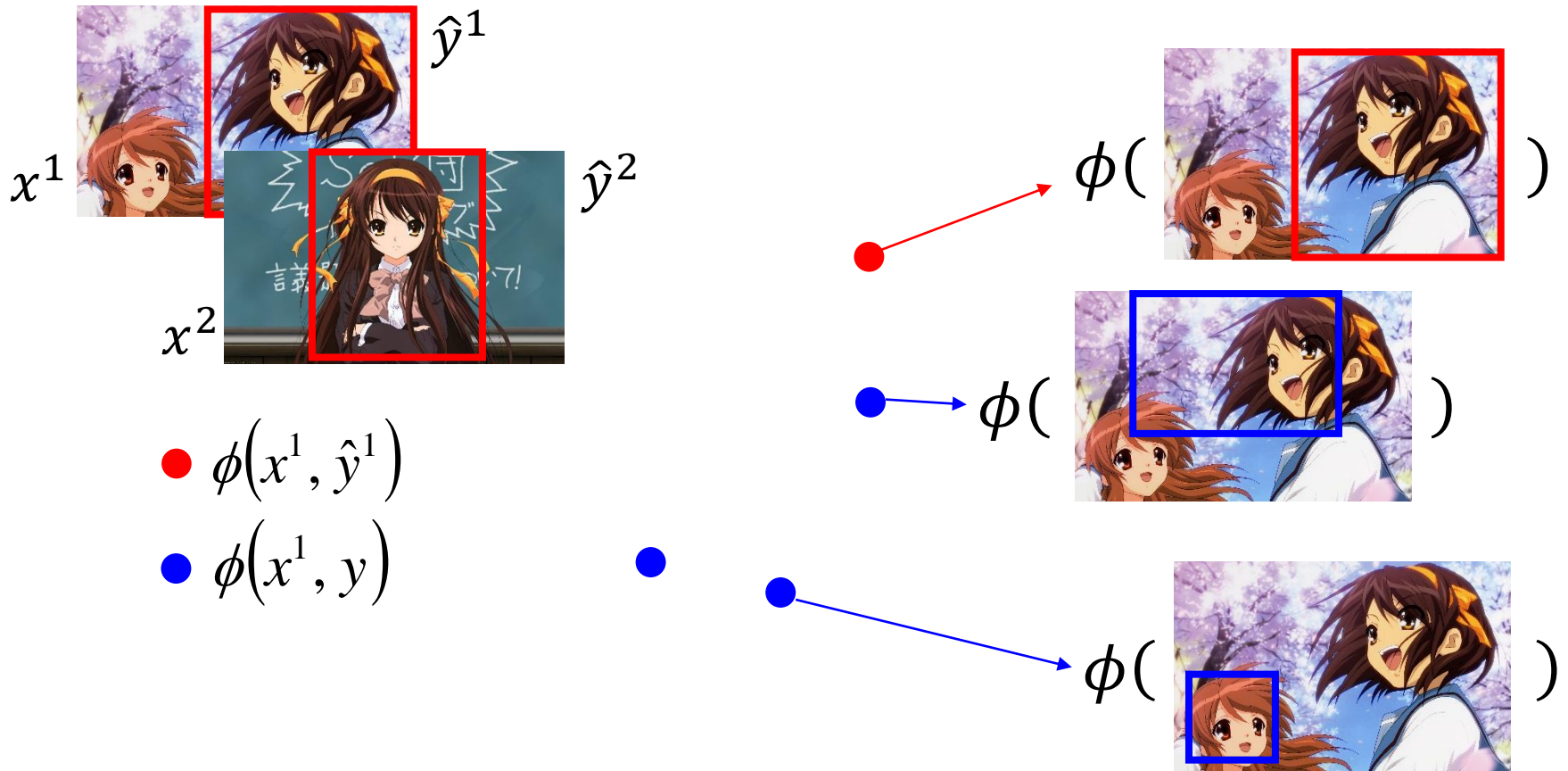
We should find  $w$  such that

$\forall r$  (All training examples)

$\forall y \in Y - \{\hat{y}^r\}$  (All incorrect label  
for r-th example)

$$w \cdot \phi(x^r, \hat{y}^r) > w \cdot \phi(x^r, y)$$

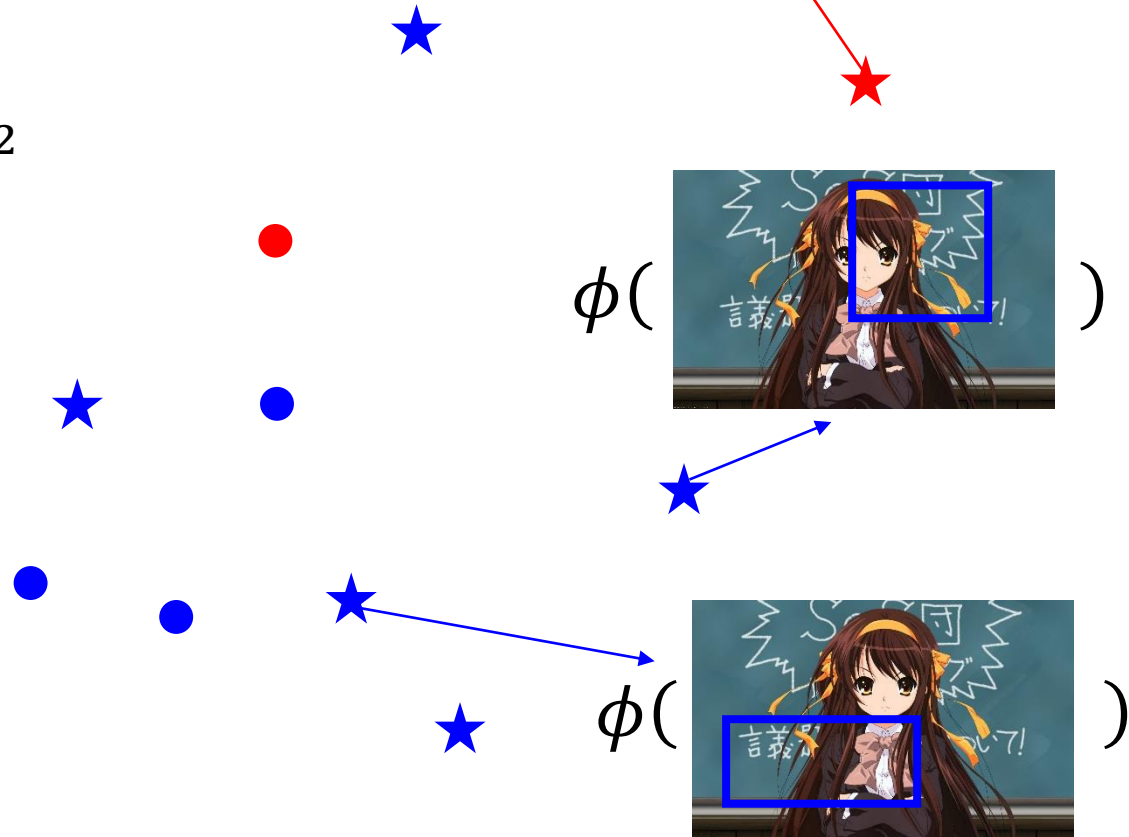
# Structured Linear Model: Problem 3



# Structured Linear Model: Problem 3



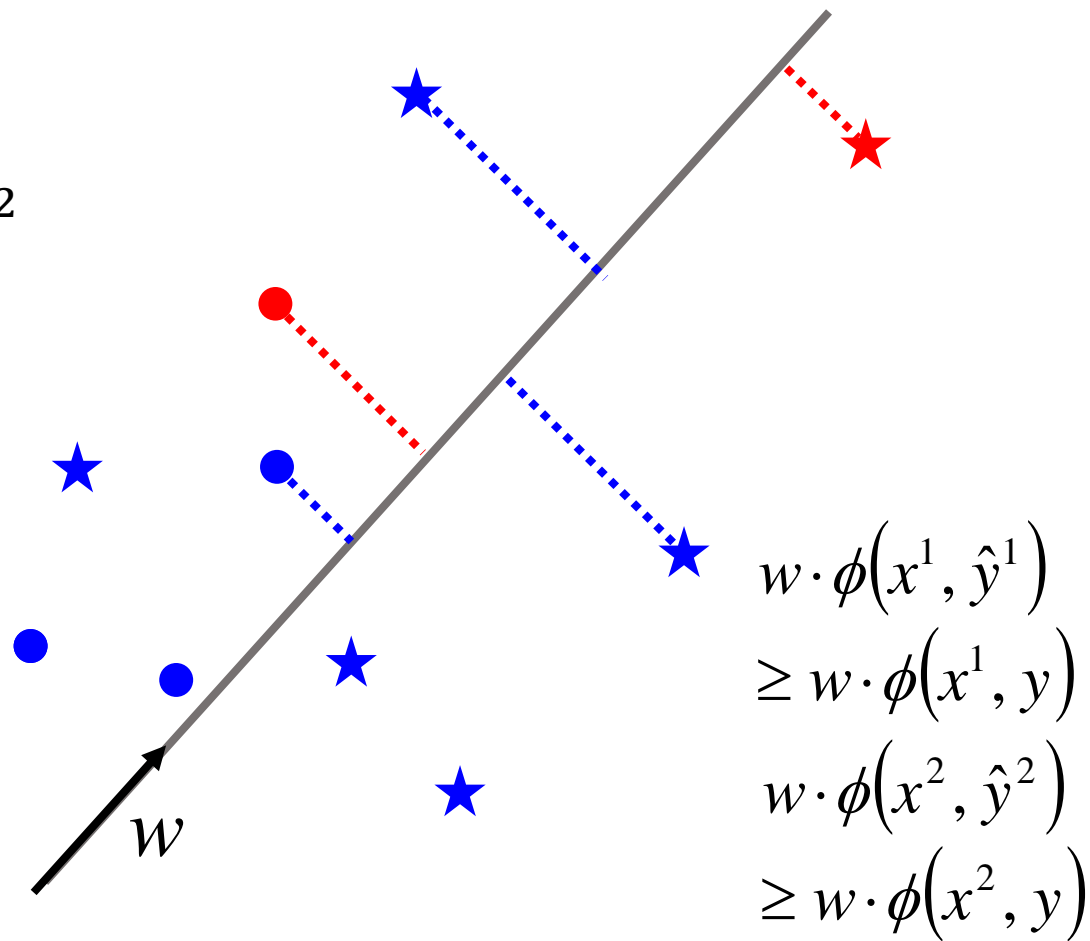
- $\phi(x^1, \hat{y}^1)$
- $\phi(x^1, y)$
- ★  $\phi(x^2, \hat{y}^2)$
- ★  $\phi(x^2, y)$



# Structured Linear Model: Problem 3



- $\phi(x^1, \hat{y}^1)$
- $\phi(x^1, y)$
- ★  $\phi(x^2, \hat{y}^2)$
- ★  $\phi(x^2, y)$




# Solution of Problem 3

Difficult?

Not as difficult as expected

# Algorithm

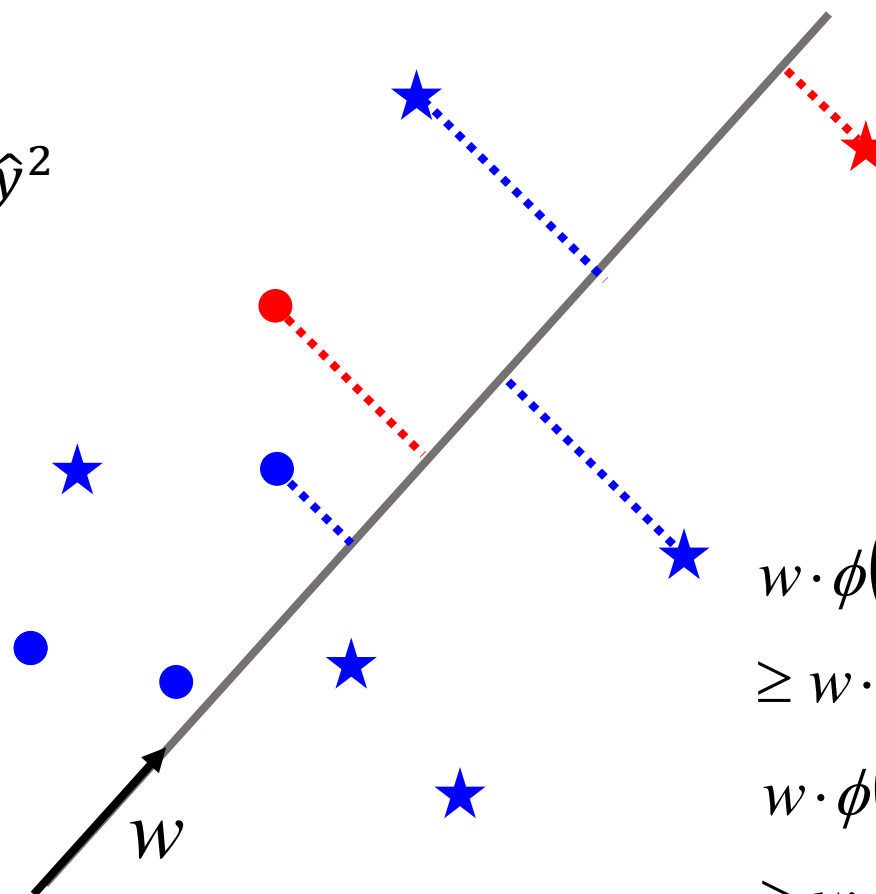
Will it terminate?

- **Input**: training data set  $\{(x^1, \hat{y}^1), (x^2, \hat{y}^2), \dots, (x^r, \hat{y}^r), \dots\}$
- **Output**: weight vector  $w$
- **Algorithm**: Initialize  $w = 0$ 
  - do
    - For each pair of training example  $(x^r, \hat{y}^r)$ 
      - Find the label  $\tilde{y}^r$  maximizing  $w \cdot \phi(x^r, y)$ 
$$\tilde{y}^r = \arg \max_{y \in Y} w \cdot \phi(x^r, y) \text{ (question 2)}$$
      - If  $\tilde{y}^r \neq \hat{y}^r$ , update  $w$ 
$$w \rightarrow w + \phi(x^r, \hat{y}^r) - \phi(x^r, \tilde{y}^r)$$
  - until  $w$  is not updated  We are done!

# Algorithm - Example



- $\phi(x^1, \hat{y}^1)$
- $\phi(x^1, y)$
- ★  $\phi(x^2, \hat{y}^2)$
- ★  $\phi(x^2, y)$



$$\begin{aligned} w \cdot \phi(x^1, \hat{y}^1) &\geq w \cdot \phi(x^1, y) \\ w \cdot \phi(x^2, \hat{y}^2) &\geq w \cdot \phi(x^2, y) \end{aligned}$$

# Algorithm - Example

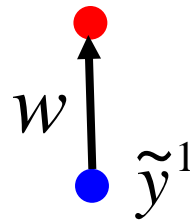
Initialize  $w = 0$

pick  $(x^1, \hat{y}^1)$

$$\tilde{y}^1 = \arg \max_{y \in Y} w \cdot \phi(x^1, y)$$

If  $\tilde{y}^1 \neq \hat{y}^1$ , update  $w$

$$w \rightarrow w + \phi(x^1, \hat{y}^1) - \phi(x^1, \tilde{y}^1)$$



●  $\phi(x^1, \hat{y}^1)$

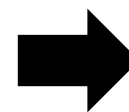
●  $\phi(x^1, y)$

★  $\phi(x^2, \hat{y}^2)$

★  $\phi(x^2, y)$



Because  $w=0$  at this time,  $\phi(x^1, y)$  always 0



Random pick one point as  $\tilde{y}^r$



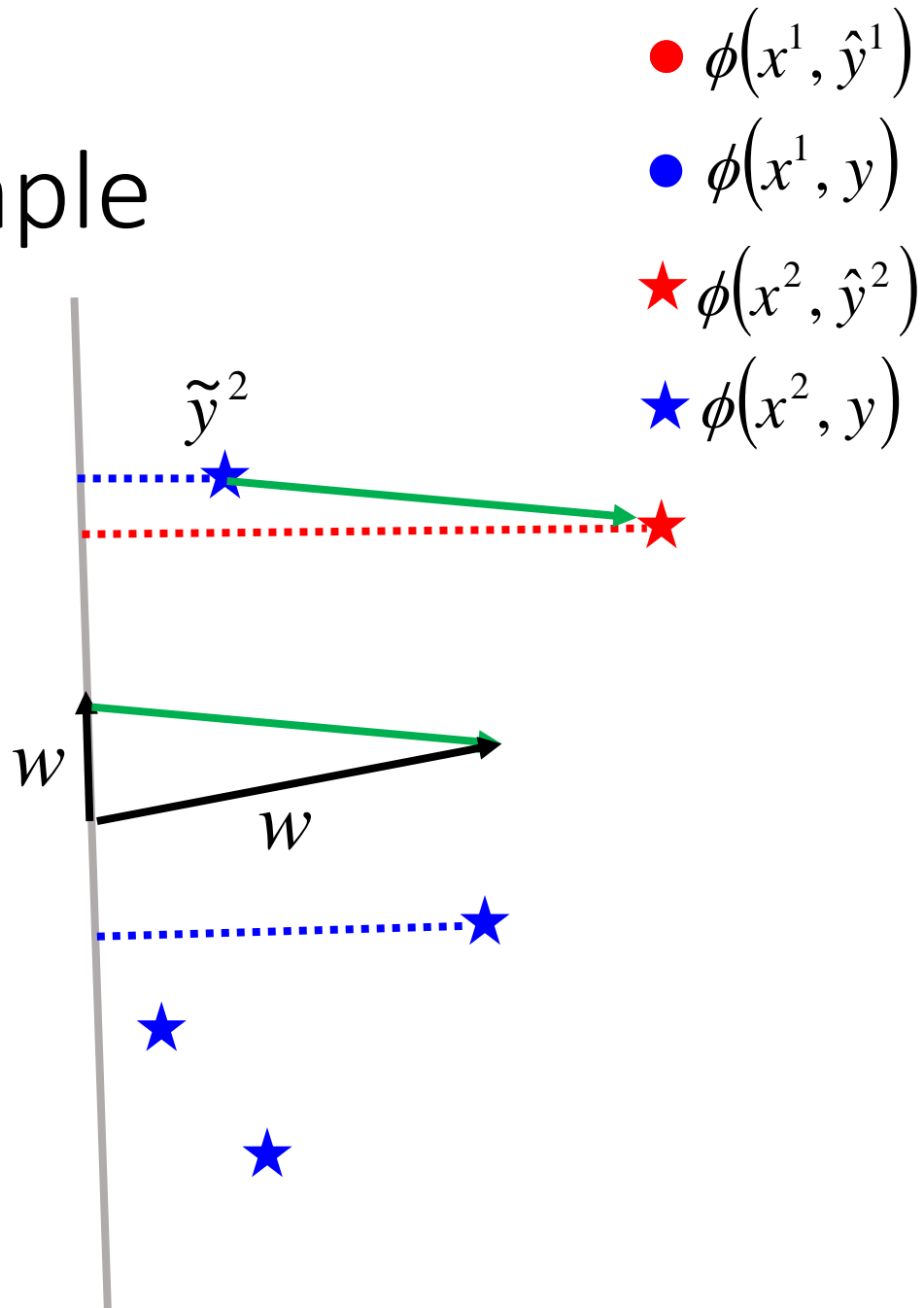
# Algorithm - Example

pick  $(x^2, \hat{y}^2)$

$$\tilde{y}^2 = \arg \max_{y \in Y} w \cdot \phi(x^2, y)$$

If  $\tilde{y}^2 \neq \hat{y}^2$ , update  $w$

$$w \rightarrow w + \phi(x^2, \hat{y}^2) - \phi(x^2, \tilde{y}^2)$$



# Algorithm - Example

●  $\phi(x^1, \hat{y}^1)$

●  $\phi(x^1, y)$

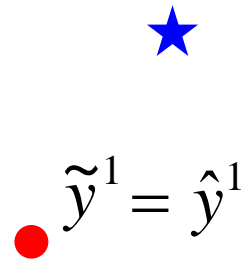
★  $\phi(x^2, \hat{y}^2)$

★  $\phi(x^2, y)$

pick  $(x^1, \hat{y}^1)$  again

$$\tilde{y}^1 = \arg \max_{y \in Y} w \cdot \phi(x^1, y)$$

$\tilde{y}^1 = \hat{y}^1$  ➡ do not update  $w$



★  $\tilde{y}^2 = \hat{y}^2$

pick  $(x^2, \hat{y}^2)$  again

$$\tilde{y}^2 = \arg \max_{y \in Y} w \cdot \phi(x^2, y)$$

$\tilde{y}^2 = \hat{y}^2$  ➡ do not update  $w$

$$w \cdot \phi(x^1, \hat{y}^1)$$

$$\geq w \cdot \phi(x^1, y)$$

$$w \cdot \phi(x^2, \hat{y}^2)$$

$$\geq w \cdot \phi(x^2, y)$$


So we are done

# Assumption: Separable

- There exists a weight vector  $\hat{w}$   $\|\hat{w}\| = 1$

$\forall r$  (All training examples)

$\forall y \in Y - \{\hat{y}^r\}$  (All incorrect label for an example)


$$\hat{w} \cdot \phi(x^r, \hat{y}^r) \geq \hat{w} \cdot \phi(x^r, y) \quad (\text{The target exists})$$
$$\hat{w} \cdot \phi(x^r, \hat{y}^r) \geq \hat{w} \cdot \phi(x^r, y) + \delta$$

# Assumption: Separable

$$\hat{w} \cdot \phi(x^r, \hat{y}^r) \geq \hat{w} \cdot \phi(x^r, y) + \delta$$

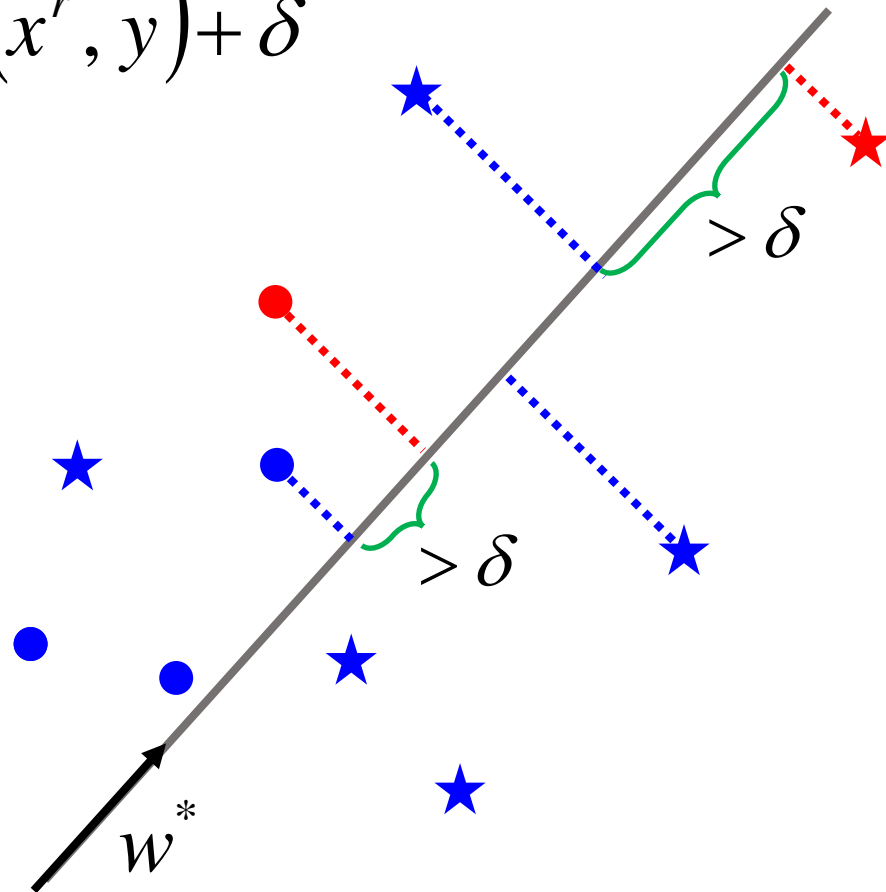
●  $\phi(x^1, \hat{y}^1)$

●  $\phi(x^1, y)$

★  $\phi(x^2, \hat{y}^2)$

★  $\phi(x^2, y)$

.....



# Proof of Termination

w is updated **once it sees a mistake**

$$w^0 = 0 \rightarrow w^1 \rightarrow w^2 \rightarrow \dots \rightarrow w^k \rightarrow w^{k+1} \rightarrow \dots$$

$$w^k = w^{k-1} + \phi(x^n, \hat{y}^n) - \phi(x^n, \tilde{y}^n) \text{ (the relation of } w^k \text{ and } w^{k-1})$$

Proof that: The angle  $\rho_k$  between  $\hat{w}$  and  $w_k$  is smaller as k increases

Analysis  $\cos \rho_k$  (larger and larger?)  $\cos \rho_k = \frac{\hat{w} \cdot w^k}{\|\hat{w}\| \cdot \|w^k\|}$

$$\begin{aligned} \hat{w} \cdot w^k &= \hat{w} \cdot (w^{k-1} + \phi(x^n, \hat{y}^n) - \phi(x^n, \tilde{y}^n)) \\ &= \hat{w} \cdot w^{k-1} + \underbrace{\hat{w} \cdot \phi(x^n, \hat{y}^n) - \hat{w} \cdot \phi(x^n, \tilde{y}^n)}_{\geq \delta \text{ (Separable)}} \geq \hat{w} \cdot w^{k-1} + \delta \end{aligned}$$

# Proof of Termination

w is updated **once it sees a mistake**

$$w^0 = 0 \rightarrow w^1 \rightarrow w^2 \rightarrow \dots \rightarrow w^k \rightarrow w^{k+1} \rightarrow \dots$$

$$w^k = w^{k-1} + \phi(x^n, \hat{y}^n) - \phi(x^n, \tilde{y}^n) \quad (\text{the relation of } w^k \text{ and } w^{k-1})$$

Proof that: The angle  $\rho_k$  between  $\hat{w}$  and  $w_k$  is smaller as k increases

Analysis  $\cos \rho_k$  (larger and larger?)

$$\cos \rho_k = \frac{\hat{w} \cdot w^k}{\|\hat{w}\| \cdot \|w^k\|}$$

$$\hat{w} \cdot w^k \geq \hat{w} \cdot w^{k-1} + \delta$$

$$\left. \begin{array}{l} \hat{w} \cdot w^1 \geq \hat{w} \cdot w^0 + \delta \\ \hat{w} \cdot w^2 \geq \hat{w} \cdot w^1 + \delta \quad \dots \end{array} \right\} \hat{w} \cdot w^k \geq k\delta$$

$$\left. \begin{array}{l} \hat{w} \cdot w^1 \geq \delta \\ \hat{w} \cdot w^2 \geq 2\delta \quad \dots \end{array} \right\} \text{(so what)}$$

# Proof of Termination

$$\cos \rho_k = \frac{\hat{w}}{\|\hat{w}\|} \cdot \frac{w^k}{\|w^k\|} \quad w^k = w^{k-1} + \phi(x^n, \hat{y}^n) - \phi(x^n, \tilde{y}^n)$$

$$\begin{aligned} \|w^k\|^2 &= \|w^{k-1} + \phi(x^n, \hat{y}^n) - \phi(x^n, \tilde{y}^n)\|^2 \\ &= \|w^{k-1}\|^2 + \underbrace{\|\phi(x^n, \hat{y}^n) - \phi(x^n, \tilde{y}^n)\|^2}_{> 0} + \underbrace{2w^{k-1} \cdot (\phi(x^n, \hat{y}^n) - \phi(x^n, \tilde{y}^n))}_{? < 0 \text{ (mistake)}} \end{aligned}$$

Assume the distance between any two feature vector is smaller than R

$$\leq \|w^{k-1}\| + R^2$$

$$\begin{aligned} \|w^1\|^2 &\leq \|w^0\|^2 + R^2 = R^2 \\ \|w^2\|^2 &\leq \|w^1\|^2 + R^2 \leq 2R^2 \\ &\dots \\ \|w^k\|^2 &\leq kR^2 \end{aligned}$$

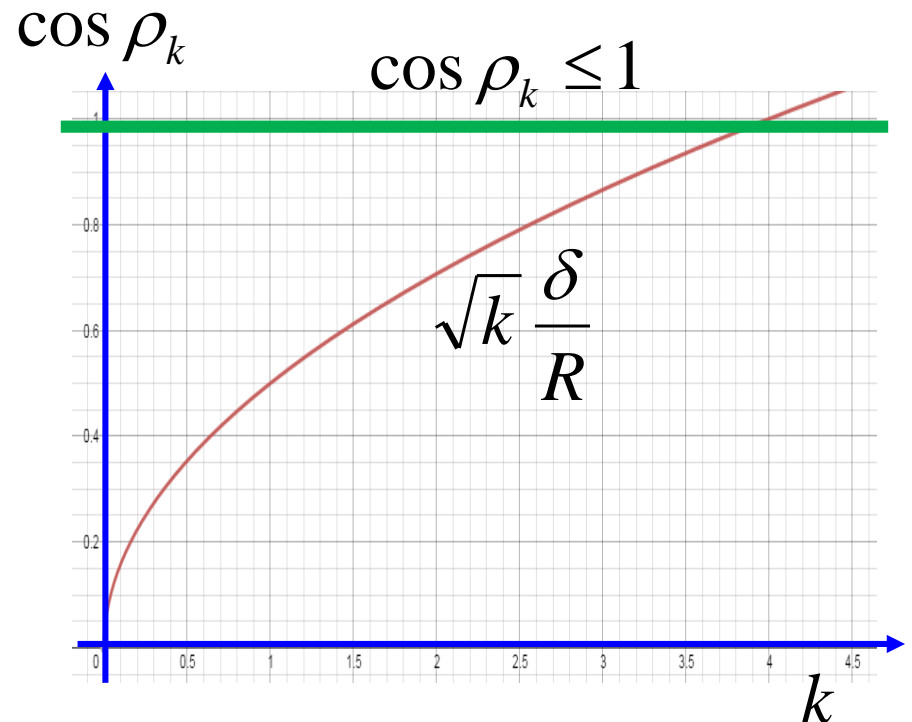
# Proof of Termination

$$\cos \rho_k = \frac{\hat{w} \cdot w^k}{\|\hat{w}\| \cdot \|w^k\|} \quad \hat{w} \cdot w^k \geq k\delta \quad \|w^k\|^2 \leq kR^2$$

$$\geq \frac{k\delta}{\sqrt{kR^2}} = \sqrt{k} \frac{\delta}{R}$$

$$\sqrt{k} \frac{\delta}{R} \leq 1$$

$$k \leq \left(\frac{R}{\delta}\right)^2$$





# Proof of Termination

$$k \leq \left( \frac{R}{\delta} \right)^2$$

The largest distances between features

Normalization

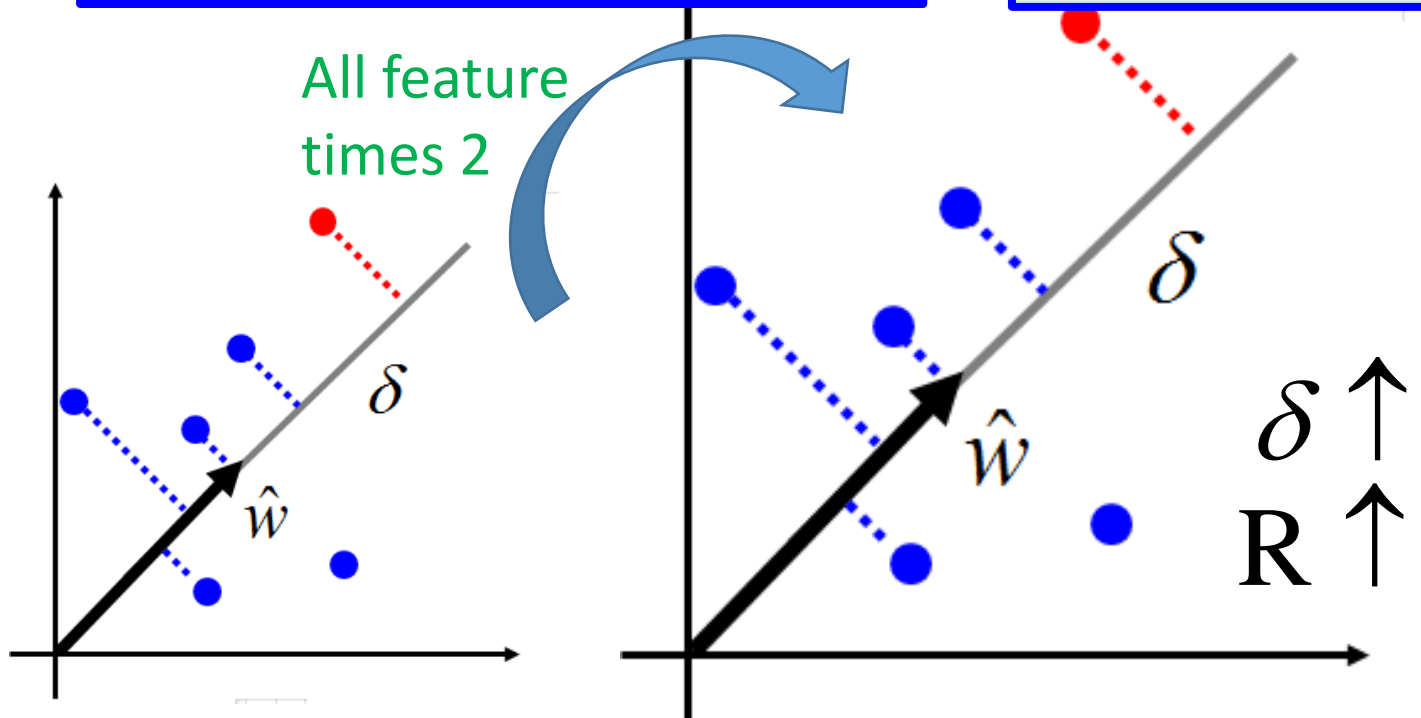
Margin: Is it easy to separate red points from the blue ones

Larger margin, less update

All feature times 2

•  $\phi(x^r, \hat{y}^r)$

•  $\phi(x^r, y)$



# Structured Linear Model: Reduce 3 Problems to 2

## Problem 1: Evaluation

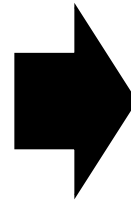
- How to define  $F(x,y)$

## Problem 2: Inference

- How to find the  $y$  with the largest  $F(x,y)$

## Problem 3: Training

- How to learn  $F(x,y)$



$$F(x,y) = w \cdot \phi(x,y)$$

## Problem A: Feature

- How to define  $\phi(x,y)$

## Problem B: Inference

- How to find the  $y$  with the largest  $w \cdot \phi(x,y)$